

## EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L2	2	((plurality serveral) with marking with devices) and (inspect \$3 with surface) and (body with paint\$3) and ((optical with picture with tak\$3) camera)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/24 23:51
L3	0	((plurality serveral) with marking with heads) and (inspect\$3 with surface) and (body with paint\$3) and ((optical with picture with tak\$3) camera)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/24 23:58
L4	0	((plurality serveral) with marking with head) and (inspect\$3 with surface) and (body with paint\$3) and ((optical with picture with tak\$3) camera)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/24 23:59
L5	2	(marking with heads) and (inspect\$3 with surface) and (body with paint\$3) and ((optical with picture with tak\$3) camera)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/24 23:59
L6	7	"702"/\$.ccls. and (((optical with picture with tak\$3) camera) with (position location) with data) and (inspect \$3 with surface) and (surface with defect)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/25 00:39
S1	0	(location position) with flaw with ((three adj1 dimensional) three-dimensional 3D) with surface	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/20 15:44

S2	32	((location position) with flaw with surface) and ((three adj1 dimensional) three-dimensional 3D)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/20 15:46
S3	16	S2 and ((optical with picture with tak\$3) camera)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/20 15:49
S4	2	S2 and (((optical with picture with tak\$3) camera) with flaw)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/20 15:49
S5	1	10/589371	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/20 15:58
S6	0	S4 and (((optical with picture with tak\$3) camera) with imag\$3 with propt\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/20 16:00
S7	0	S3 and (((optical with picture with tak\$3) camera) with imag\$3 with propt\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/20 16:00
S8	0	S4 and (optical with imag\$3 with propt\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/20 16:02
S9	0	S3 and (optical with imag\$3 with propt\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/20 16:02

S10	9	S3 and (imag\$3 with proptert\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/20 16:02
S11	0	S4 and (imag\$3 with proptert\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/20 16:02
S12	1	S5 and (imag\$3 with proptert\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/20 16:04
S13	1	S12 and (((optical with picture with tak\$3) camera) with flaw)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/20 16:05
S14	4	("6320654" "2003139836").pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/20 16:06
S15	4	("6320654" "20031039836" "6266138").pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/20 16:29
S16	4	("6320654" "200301039836" "6266138").pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/22 11:08
S17	55	(surface with defect\$3) and (((optical with picture with tak\$3) camera) with imag\$3 with proptert\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/22 11:38

S18	1	S17 and (paint\$3 with surface)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/22 11:40
S19	16	S17 and (inspect\$3 with surface)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/22 11:41
S20	1	S17 and (inspect\$3 with surface with body)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/22 11:43
S21	1	S17 and (inspect\$3 with surface) and (surface with body)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/22 11:44
S22	7	((optical with picture with tak\$3) camera) with imag\$3 with propret\$4) and (inspect\$3 with surface) and (surface with body)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/22 11:44
S23	42	((optical with picture with tak\$3) camera) and (optical with imag\$3 with propret\$4) and (inspect\$3 with surface) and (surface with body)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/22 11:52
S24	0	((optical with picture with tak\$3) camera) and (optical with imag\$3 with propret\$4) and (inspect\$3 with surface) and (surface with body with vehicle)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/22 11:53

S25	3	((optical with picture with tak\$3) camera) and (optical with imag\$3 with propt\$4) and (inspect\$3 with surface) and (surface with body with paint\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/22 11:53
S26	1	"6320654".pn. and (surface near2 defect)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/22 17:27
S27	1	"6320654".pn. and (camera with (position location))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/22 18:18
S28	1	((optical with picture with tak\$3) camera) and (((optical with picture with tak\$3) camera) with position with data) and (surface with position with data) and (inspect\$3 with surface) and (surface with body with paint\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/22 18:59
S29	1	"6320654".pn. and (data with (position location))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/22 19:05
S30	0	"6495833".pn. and (camera with (position location))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/22 19:06
S31	2	((optical with picture with tak\$3) camera) with (position location)) and (optical with imag\$3 with propt\$4) and (inspect\$3 with surface) and (body with paint\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/22 19:08

S32	3	((optical with picture with tak\$3) camera) with (position location)) and optical and ( imag\$3 with proper\$4) and (inspect \$3 with surface) and (body with paint\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/22 19:09
S33	22	((optical with picture with tak\$3) camera) with (position location)) and (inspect \$3 with surface) and (body with paint\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/22 19:14
S34	5	((optical with picture with tak\$3) camera) with (position location) with data) and (inspect \$3 with surface) and (body with paint\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/22 19:14
S35	7	((optical with picture with tak\$3) camera) with (position location)) and (inspect \$3 with surface) and (body with paint\$3 with vehicle)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/22 19:15
S36	0	((optical with picture with tak\$3) camera) with (position location)) and (inspect \$3 with surface) and (body with paint\$3 with vehicle) and (imag \$3 with (property properties))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/22 19:18
S37	1	((optical with picture with tak\$3) camera) with (position location) with data) and (inspect \$3 with surface) and (body with paint\$3 with vehicle)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/23 09:39
S38	2	((optical with picture with tak\$3) camera) with (position location) with data) and (inspect \$3 with surface) and (body with paint\$3) and (automobile vehicle)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/23 09:40

S39	5	((optical with picture with tak\$3) camera) with (position location) with (calculat\$3 measur \$6)) and (surface with defect) and (body with paint\$3) and (automobile vehicle)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/23 09:50
S40	8	((optical with picture with tak\$3) camera) near2 (position location) ) and (surface with defect) and (body with paint\$3) and (automobile vehicle)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/23 09:58
S41	1	((optical with picture with tak\$3) camera) near2 (position location) ) and (surface with defect) and (body with paint\$3) and (automobile vehicle) and (position near2 data)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/23 10:04
S42	2	((optical with picture with tak\$3) camera) with (position location)) and (inspect \$3 with surface) and (body with paint\$3 with vehicle) and (position near2 data)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/23 10:08
S43	0	((optical with picture with tak\$3) camera) near2 position) and ((defect flaw) near2 position) and (inspect \$3 with surface) and (body with paint\$3) and (automobile vehicle) and robot	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/23 11:35
S44	1	((optical with picture with tak\$3) camera CCD) near2 position) and (inspect\$3 with surface) and (body with paint\$3) and (automobile vehicle) and robot	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/23 11:37

S45	5	((optical with picture with tak\$3) camera CCD) near2 position) and (inspect\$3 with surface) and (body with paint\$3) and (automobile vehicle)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/23 11:39
S46	4	((relative relat\$3) with ((optical with picture with tak\$3) camera CCD) with position with surface) and (inspect\$3 with surface) and (body with paint\$3) and (automobile vehicle)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/23 11:45
S47	4	((relative relat\$3) with ((optical with picture with (tak\$3 device)) camera CCD) with position with surface) and (inspect\$3 with surface) and (body with paint\$3) and (automobile vehicle)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/23 11:51
S48	4	((relative relat\$3) with ((optical with (picture image) with (tak\$3 device)) camera CCD) with position with surface) and (inspect\$3 with surface) and (body with paint\$3) and (automobile vehicle)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/23 11:52
S49	1	((relative relat\$3) with data with ((optical with (picture image) with (tak\$3 device)) camera CCD) with position with surface) and (inspect\$3 with surface) and (body with paint\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/23 11:55
S50	4	((relative relat\$3) with data with ((optical with (picture image) with (tak\$3 device)) camera CCD) with position with surface) and (inspect\$3 with surface) and (surface with defect)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/23 11:55



S51	0	((optical with (picture image) with (tak\$3 device)) camera CCD) near2 position near2 data) and (inspect\$3 with surface) and painted and (surface with defect)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/23 12:00
S52	0	((optical with (picture image) with (tak\$3 device)) camera CCD) near2 position) and (position near2 data) and (inspect\$3 with surface) and painted and (surface with defect)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/23 12:02
S53	44	((optical with (picture image) with (tak\$3 device)) camera CCD) near2 position) and (position near2 data) and (inspect\$3 with surface) and (surface with defect)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/23 12:03
S54	6	((optical with (picture image) with (tak\$3 device)) camera CCD) near2 position) and (position near2 surface) and (inspect\$3 with surface) and (surface with defect) and painted	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/23 12:25
S55	6	((optical with (picture image) with (tak\$3 device)) camera CCD) near2 position) and (position near2 surface) and (inspect\$3 with surface) and (surface with defect) and painted and (defect near2 position)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/23 12:40
S56	2	((optical with picture with tak\$3) camera CCD) with (position location)) and (inspect \$3 with surface) and (body with paint\$3 with vehicle) and (position near2 data)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/23 12:41

S57	2	("6320654" "2003139836").pn. and position	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/24 13:57
S58	2	((optical with picture with tak\$3) camera) and (optical with propert\$4) and (inspect \$3 with surface) and ( body with paint\$3) and (robot (displac\$4 near2 device))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/24 16:16
S59	7	((optical with picture with tak\$3) camera) and (optical with imag \$3) and (inspect\$3 with surface) and ( body with paint\$3) and (robot (displac\$4 near2 device))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/24 16:17
S60	5	((optical with picture with tak\$3) camera) and (optical with imag \$3) and (inspect\$3 with surface) and ( body with paint\$3) and (robot (displac\$4 near2 device)) and mark\$3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/24 16:17
S61	2	((optical with picture with tak\$3) camera) with (position location)) and (inspect \$3 with surface) and (body with paint\$3) and (marking same (robot (displac\$4 with device)))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/24 16:44
S62	2	((optical with picture with tak\$3) camera) and (marking near2 head) and (inspect\$3 with surface) and (body with paint\$3) and (robot (displac\$4 with device))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/24 16:50

S63	1	"5716262".pn. and ((optical with picture with tak\$3) camera) and (marking near2 head) and (inspect\$3 with surface) and (body with paint\$3) and (robot (displac\$4 with device))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/24 16:52
S64	2	EP-1092973-\$.did.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/24 17:37
S65	4	((optical with picture with tak\$3) camera) and ((position location) with data) and (inspect \$3 with surface) and (body with paint\$3) and ((calibrat\$3 adjust \$3) with ((optical with picture with tak\$3) camera))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/24 18:43
S66	11	(inspect\$3 with surface) and (body with paint\$3) and ((calibrat\$3 adjust\$3) with ((optical with picture with tak\$3) camera))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/24 18:46
S67	1	"5716262".pn. and (control\$4 with arm)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/04/24 19:27

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